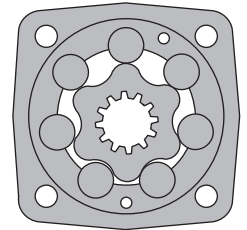
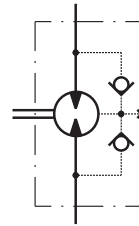




APPLICATION

- » Sawmill machines
- » Woodworking machines
- » Metal working machines
- » Agriculture machines
- » Road building machines
- » Mining machinery
- » Food industries
- » Special vehicles etc.



CONTENTS

Specification data	5
Dimensions and mounting	6
Permissible shaft loads	6
Shaft extensions	7
Order code	7

OPTIONS

- » Model - Disc valve, roll-gerotor
- » Wheel mount
- » Side and rear ports
- » Shafts - straight, splined and tapered
- » Metric and BSPP ports
- » Other special features

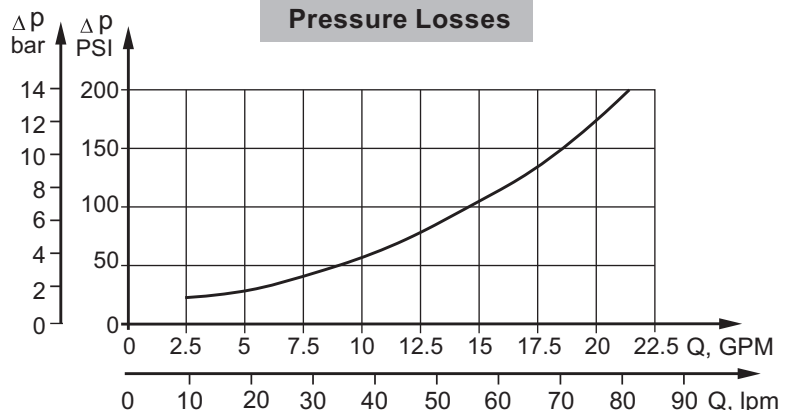
GENERAL

Max. Displacement, cm ³ /rev [in ³ /rev]	397 [24.2]
Max. Speed, [RPM]	560
Max. Torque, daNm [lb-in]	cont.: 90 [7965] int: 110 [9735]
Max. Output, kW [HP]	24 [32.2]
Max. Pressure Drop, bar [PSI]	cont.: 200 [2900] int: 225 [3270]
Max. Oil Flow, lpm [GPM]	90 [24]
Min. Speed, [RPM]	5
Pressure fluid	Mineral based- HLP(DIN 51524) or HM(ISO 6743/4)
Temperature range, °C [°F]	-40÷140 [-40÷284]
Optimal Viscosity range, mm ² /s [SUS]	20÷75 [98÷347]
Filtration	ISO code 20/16 (Min. recommended fluid filtration of 25 micron)

Oil flow in drain line

Pressure drop bar [PSI]	Viscosity mm ² /s [SUS]	Oil flow in drain line lpm [GPM]
140 [2030]	20 [98]	1,5 [.396]
	35 [164]	1 [.264]
210 [3045]	20 [98]	3 [.793]
	35 [164]	2 [.528]

Pressure Losses



SPECIFICATION DATA

Type		MSWM 160	MSWM 200	MSWM 250	MSWM 315	MSWM 400
Displacement, cm ³ /rev [in ³ /rev]		159,7 [9.74]	200 [12.2]	250 [15.3]	314,9 [19.2]	397 [24.2]
Max. Speed, [RPM]	Cont.	470	375	300	240	185
	Int.*	560	450	360	285	225
Max. Torque daNm [lb-in]	Cont.	46 [4070]	56,6 [5010]	70,8 [6270]	90,0 [7965]	90,0 [7965]
	Int.*	51,5 [4560]	64,5 [5710]	80,6 [7135]	96,0 [8500]	97,0 [8585]
	Peak**	51,5 [4560]	65 [5755]	80,6 [7135]	108 [9560]	110 [9735]
Max. Output kW [HP]	Cont.	18,6 [24.9]	18,1 [24.3]	18,0 [24.1]	17,0 [22.8]	11,0 [14.7]
	Int.*	24,0 [32.2]	24,0 [32.2]	23,8 [31.9]	20,2 [27.1]	12 [16.1]
Max. Pressure Drop bar [PSI]	Cont.	200 [2900]	200 [2900]	200 [2900]	200 [2900]	160 [2320]
	Int.*	225 [3270]	225 [3270]	225 [3270]	220 [3190]	175 [2540]
	Peak**	225 [3270]	225 [3270]	225 [3270]	225 [3270]	200 [2900]
Max. Oil Flow lpm [GPM]	Cont.	75 [20]	75 [20]	75 [20]	75 [20]	75 [20]
	Int.*	90 [24]	90 [24]	90 [24]	90 [24]	90 [24]
Max. Inlet Pressure bar [PSI]	Cont.	210 [3045]	210 [3045]	210 [3045]	210 [3045]	210 [3045]
	Int.*	250 [3625]	250 [3625]	250 [3625]	250 [3625]	250 [3625]
	Peak**	300 [4350]	300 [4350]	300 [4350]	300 [4350]	300 [4350]
Max. Return Pressure with Drain Line bar [PSI]	Cont.	140 [2030]	140 [2030]	140 [2030]	140 [2030]	140 [2030]
	Int.*	175 [2540]	175 [2540]	175 [2540]	175 [2540]	175 [2540]
	Peak**	210 [3045]	210 [3045]	210 [3045]	210 [3045]	210 [3045]
Max. Starting Pressure with Unloaded Shaft, bar [PSI]		10 [145]	10 [145]	10 [145]	10 [145]	10 [145]
Min. Starting Torque daNm [lb-in]		36,9 [3270]	46,2 [4090]	58,0 [5135]	73,8 [6530]	72,0 [6370]
Min. Speed***, [RPM]		6	6	6	5	5
Weight, kg [lb]		15,3 [33.7]	15,7 [34.6]	16,2 [35.7]	16,9 [37.3]	17,8 [39.2]

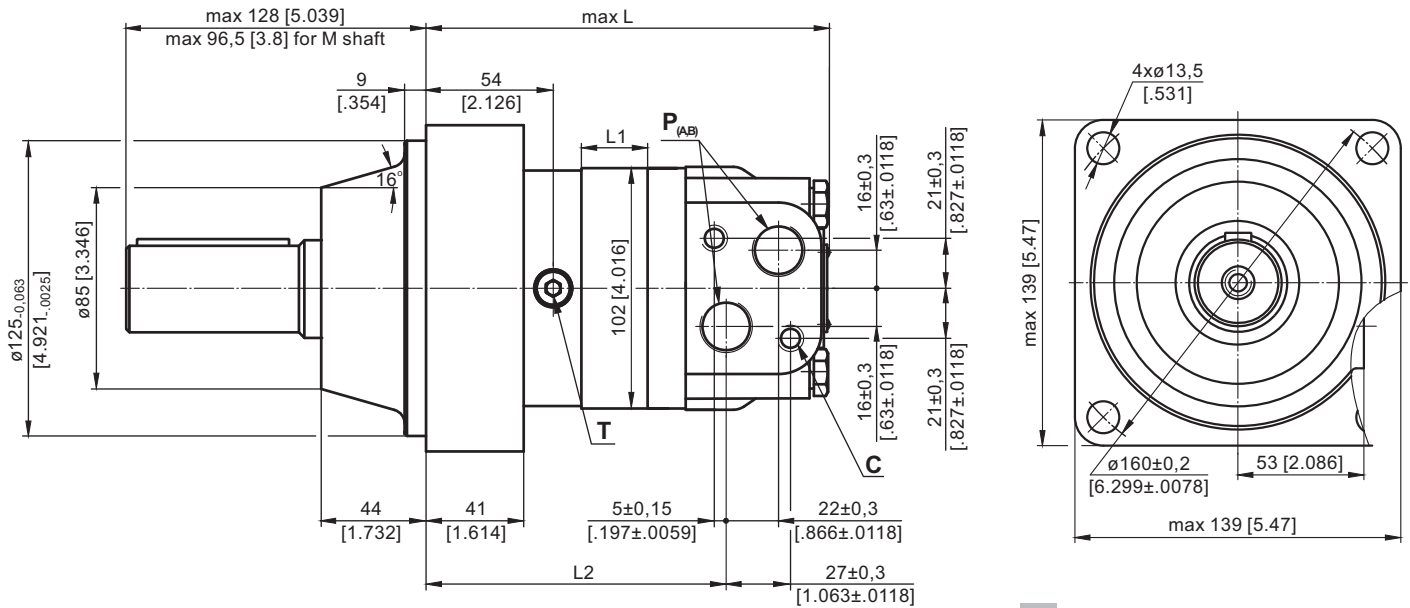
* Intermittent operation: the permissible values may occur for max. 10% of every minute.

** Peak load: the permissible values may occur for max. 1% of every minute.

*** For speeds lower than given, consult factory or your regional manager.

- Intermittent speed and intermittent pressure must not occur simultaneously.
- Recommended filtration is per ISO cleanliness code 20/16. A nominal filtration of 25 micron or better.
- Recommend using a premium quality, anti-wear type mineral based hydraulic oil HLP(DIN51524) or HM (ISO 6743/4).
If using synthetic fluids consult the factory for alternative seal materials.
- Recommended minimum oil viscosity 13 mm²/s [70 SUS] at 50°C [122°F].
- Recommended maximum system operating temperature is 82°C [180°F].
- To assure optimum motor life fill with fluid prior to loading and run at moderate load and speed for 10-15 minutes.

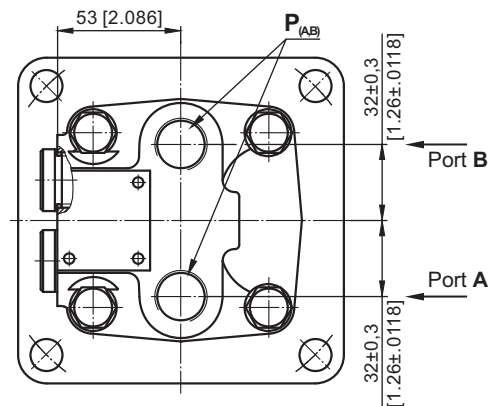
DIMENSIONS and MOUNTING DATA



- C** : 2xM10 - 12 mm [0.47 in] depth
P_(A,B) : 2xG1/2 or 2xM22x1,5 - 15 mm [0.59 in] depth
T : G 1/4 or M14x1,5 - 12 mm [0.47 in] depth (plugged)

Type	L, mm [in]	L2, mm [in]	L1, mm [in]
MSWM 160	170,5[6.71]	129,3[5.09]	27,8 [1.09]
MSWME 160	177,5[6.99]		
MSWM 200	177,5[6.99]	136,3[5.37]	34,8 [1.37]
MSWME 200	184,5[7.26]		
MSWM 250	186,0[7.32]	145,0[5.71]	43,5 [1.71]
MSWME 250	193,0[7.60]		
MSWM 315	197,5[7.78]	157,3[6.19]	54,8 [2.16]
MSWME 315	206,5[8.13]		
MSWM 400	212,0[8.35]	171,0[6.73]	69,4 [2.73]
MSWME 400	219,0[8.62]		

E Rear Ports



Standard Rotation

Viewed from Shaft End

Port A Pressurized - CW

Port B Pressurized - CCW

Reverse Rotation

Viewed from Shaft End

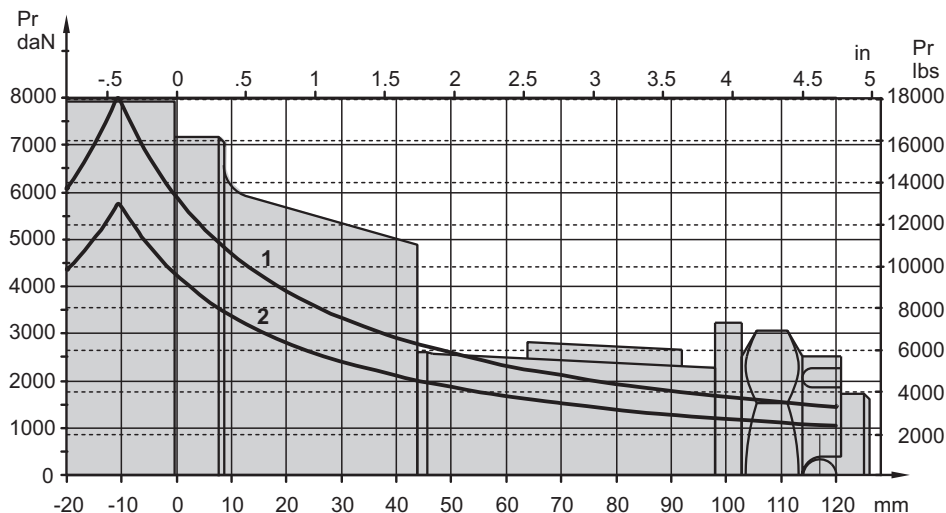
Port A Pressurized - CCW

Port B Pressurized - CW



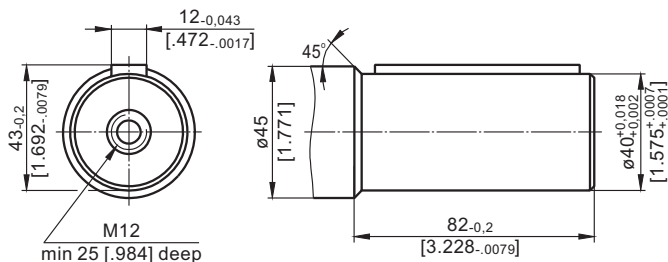
PERMISSIBLE SHAFT LOADS

The output shaft runs in tapered bearings that permit high axial and radial forces. Curve "1" shows max. radial shaft load at bearing life of 2000 hours at 100 RPM. Curve "2" shows max. radial shaft load at bearing life of 3000 hours at 200 RPM.

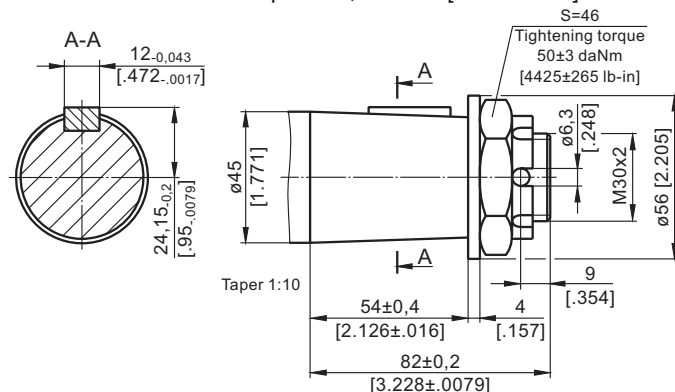


SHAFT EXTENSIONS

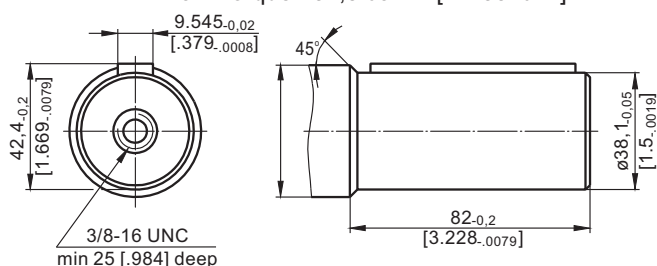
C - $\varnothing 40$ straight, Parallel key A12x8x70 DIN 6885
Max. Torque 132,8 daNm [11755 lb-in]



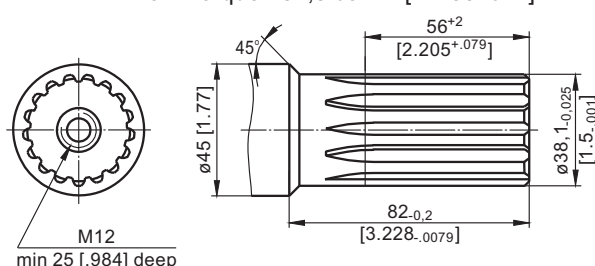
K - tapered 1:10, Parallel key B12x8x28 DIN 6885
Max. Torque 210,7 daNm [18650 lb-in]



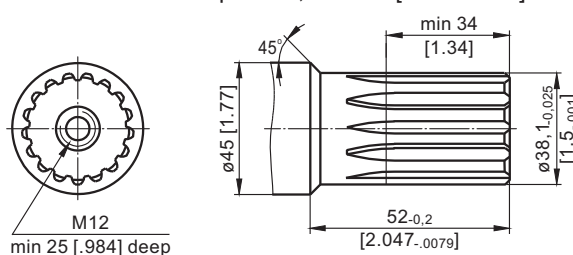
CO - $\varnothing 1\frac{1}{2}$ " straight, Parallel key $\frac{3}{8}$ "x $\frac{3}{8}$ "x $2\frac{1}{4}$ " BS46
Max. Torque 132,8 daNm [11755 lb-in]



SH - $\varnothing 1\frac{1}{2}$ " splined 17T, DP 12/24 ANSI B92.1-1976
Max. Torque 132,8 daNm [11755 lb-in]



M - $\varnothing 1\frac{1}{2}$ " splined 17T, DP 12/24 ANSI B92.1-1976
Max. Torque 132,8 daNm [11755 lb-in]



ORDER CODE

1	2	3	4	5	6
M S W M					

Pos.1 - Port type

- omit - Side ports
E - Rear ports

Pos.2 - Displacement code

- 160** - 159,7 cm³/rev [9.74 in³/rev]
200 - 200,0 cm³/rev [12.20 in³/rev]
250 - 250,0 cm³/rev [15.30 in³/rev]
315 - 314,9 cm³/rev [19.20 in³/rev]
400 - 397,0 cm³/rev [24.20 in³/rev]

Pos.4 - Shaft Extensions*

- C** - $\varnothing 40$ straight, Parallel key A12x8x70 DIN6885
CO - $\varnothing 1\frac{1}{2}$ " straight, Parallel key $\frac{3}{8}$ "x $\frac{3}{8}$ "x $2\frac{1}{4}$ " BS46
K - $\varnothing 45$ tapered 1:10, Parallel key B12x8x28 DIN6885
SH - $\varnothing 1\frac{1}{2}$ " splined 17T ANS B92.1-1976
M - $\varnothing 1\frac{1}{2}$ " splined 17T ANS B92.1-1976

Pos.4 - Ports

- omit - BSPP (ISO 228)
E - Metric (ISO 262)

Pos.5 - Additional Options (see page 69)

Pos.6 - Design Series

- omit - Factory specified

NOTES:

- * The permissible output torque for shafts must not be exceeded!

The hydraulic motors are mangano-phosphatized as standard.

MOTOR ADDITIONAL OPTIONS

Additional Options Description	Order Code	Motor type							
		MSWM	MTK	MTM	TMF	TMYF	MVM	MVMC	VMF
Speed Sensor*	RS	O	O	O	O	O	O	-	O
Reinforced motor	HD	-	S	S	S	S	S	S	S
Low Leakage	LL	O	O	O	O	O	O	O	O
Low Speed Valving	LSV	O	O	O	O	O	O	O	O
Free Running	FR	-	O	-	-	O	-	O	-
Reverse Rotation	R	O	O	O	O	O	O	O	O
Paint**	P	O	O	O	O	O	O	O	O
Corrosion Protected Paint**	PC	O	O	O	O	O	O	O	O
Special Paint***	PS	O	O	O	O	O****	O	O	O
	PCS								
Check Valves		S	O	O	-	O	O	O	-

O	Optional
-	Not applicable
S	Standard

* For sensor ordering see pages 70÷71.

** Colour at customer's request.

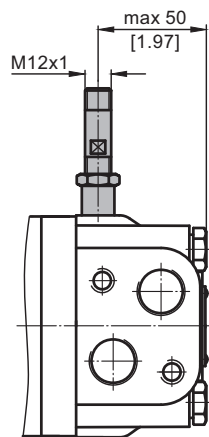
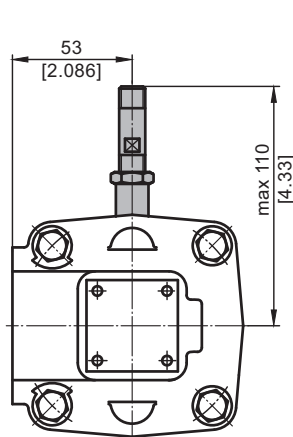
*** Non painted feeding surfaces, colour at customer's request.

**** For Port Size Version 5 only!

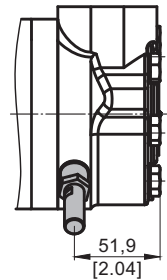
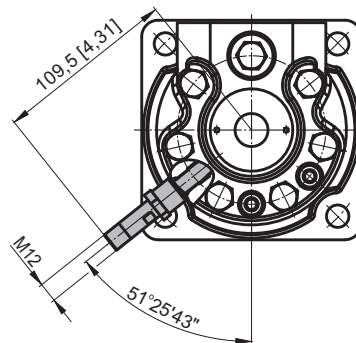
 For more information about **HD** option please contact with "M+S Hydraulic".

MOTORS WITH SPEED SENSOR

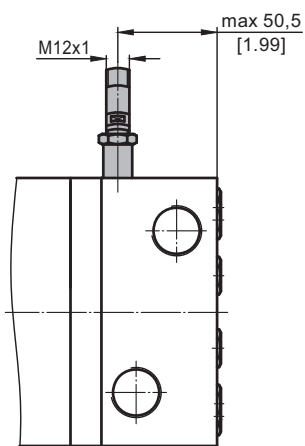
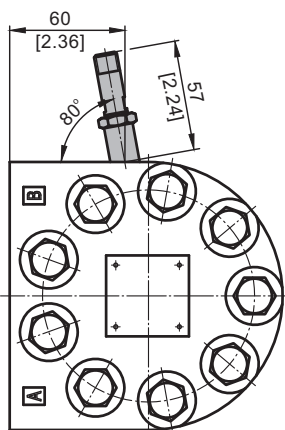
MSWM...RS



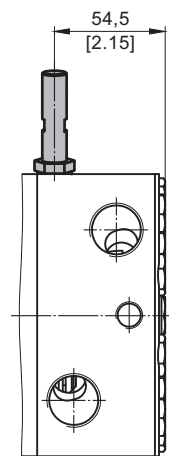
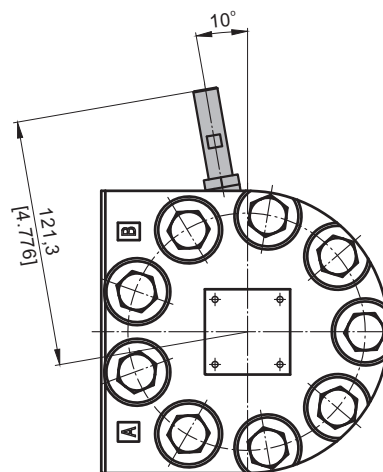
MTK...RS



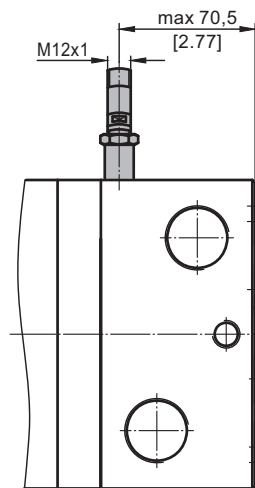
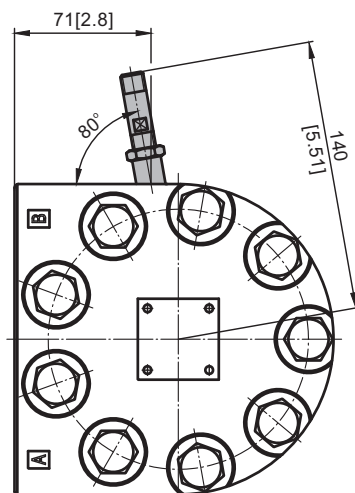
MTM...RS TMF...RS



TMYF...RS



MVM...RS VMF...RS

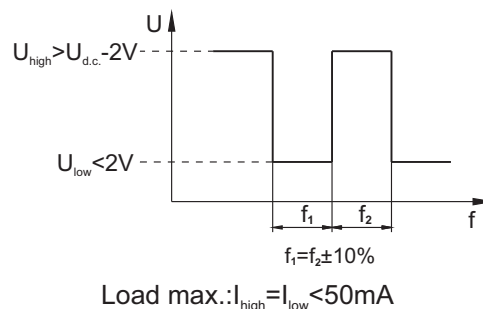


TECHNICAL DATA OF THE SPEED SENSOR

Technical data

Frequency range	0...15 000 Hz
Output	Universal PUSH PULL
Power supply	10-30 VDC (10-36 for TMYF)
Current input	<20 mA (@24 VDC)
Maximum output current	500 mA
Ambient Temperature	-40...+125°C [-40...+257°F]
Protection	IP 67
Plug connector	M12-Series
Mounting principle	ISO 6149

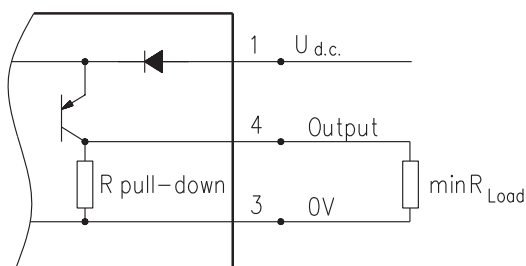
Output signal



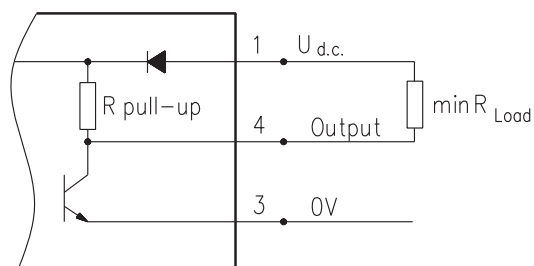
Motor type	MSWM MTK	MTM TMF, TMYF	MVM VMF
Pulses per revolution	54	84	102

Wiring diagrams

PNP

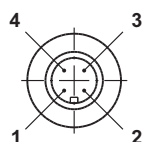


NPN



$$R_{Load} [\text{k}\Omega] = U_{d.c.} [\text{V}] / I_{max} [\text{mA}]$$

Stick type



Terminal No.	Connection	Cable Output
1	$U_{d.c.}$	Brown
2	No connection	White
3	0V	Blue
4	Output signal	Black

Order Code for Speed Sensor

Sensor Code	Electric connection
RS	Connector BINDER 713 series
RSL2,5	Cable output 3x0,25; 2,5 m [98 in] long
RSL3,5	Cable output 3x0,25; 3,5 m [138 in] long
RSL5	Cable output 3x0,25; 5 m [196 in] long
RSL10	Cable output 3x0,25; 10 m [394 in] long

NOTE: * - The speed sensor is not fitted at the factory, but is supplied in a plastic bag with the motor.
For installation see enclosed instructions.

APPLICATION CALCULATION

VEHICLE DRIVE CALCULATIONS

1. Motor speed: n [RPM]

$$n = \frac{2.65 \times V_{km} \times i}{R_m} \quad n = \frac{168 \times V_{mi} \times i}{R_{in}}$$

V_{km} - vehicle speed, km/h;

V_{mi} - vehicle speed, mil/h;

R_m - wheel rolling radius, m;

R_{in} - wheel rolling radius, in;

i - gear ratio between motor and wheels.

If no gearbox, use $i=1$.

2. Rolling resistance: RR , daN [lbs]

The resistance force resulted in wheels contact with different surfaces:

$$RR = G \times \rho$$

G - total weight loaded on vehicle, daN [lbs];

ρ - rolling resistance coefficient (Table 1).

Table 1

Rolling resistance coefficient In case of rubber tire rolling on different surfaces	
Surface	ρ
Concrete- faultless	0.010
Concrete- good	0.015
Concrete- bad	0.020
Asphalt- faultless	0.012
Asphalt- good	0.017
Asphalt- bad	0.022
Macadam- faultless	0.015
Macadam- good	0.022
Macadam- bad	0.037
Snow- 5 cm	0.025
Snow- 10 cm	0.037
Polluted covering- smooth	0.025
Polluted covering- sandy	0.040
Mud	0.037÷0.150
Sand- Gravel	0.060÷0.150
Sand- loose	0.160÷0.300

3. Grade resistance: GR , daN [lbs]

$$GR = G \times (\sin \alpha + \rho \times \cos \alpha)$$

α - gradient negotiation angle (Table 2).

Table 2

Grade %	α Degrees	Grade %	α Degrees
1%	0° 35'	12%	6° 5'
2%	1° 9'	15%	8° 31'
5%	2° 51'	20%	11° 19'
6%	3° 26'	25%	14° 3'
8%	4° 35'	32%	18°
10%	5° 43'	60%	31°

4. Acceleration force: FA , daN [lbs]

Force FA necessary for acceleration from 0 to maximum speed v and time t can be calculated with a formula:

$$FA = \frac{V_{km} \times G}{36 \times t}, [\text{daN}] \quad FA = \frac{V_{mi} \times G}{22 \times t}, [\text{lbs}]$$

FA - acceleration force, daN [lbs];

t - time, [s]

5. Tractive effort: DP , daN [lbs]

Tractive effort DP is the additional force of trailer. This value will be established as follows:

- acc. to constructor's assessment;

- as calculating forces in items 2, 3 and 4 of trailer;

the calculated sum corresponds to the tractive effort requested.

6. Total tractive effort: TE , daN [lbs]

Total tractive effort TE is total effort necessary for vehicle motion; that the sum of forces calculated in items from 2 to 5 and increased with 10% because of air resistance.

$$TE = 1,1 \times (RR + GR + FA + DP)$$

RR - force acquired to overcome the rolling resistance;

GR - force acquired to slope upwards;

FA - force acquired to accelerate (acceleration force);

DP - additional tractive effort (trailer).

7. Motor Torque moment: M , daNm [lb-in]

Necessary torque moment for every hydraulic motor:

$$M = \frac{TE \times R_m [R_{in}]}{N \times i \times \eta_m}$$

N - motor numbers;

η_m - mechanical gear efficiency (if it is available).

8. Cohesion between tire and road covering:

M_w , daNm [lb-in]

Necessary torque moment for every hydraulic motor:

$$M_w = \frac{G_w \times f \times R_m [R_{in}]}{i \times \eta_m}$$

To avoid wheel slipping, the following condition should be observed $M_w > M$

f - frictional factor;

G_w - total weight over the wheels, daN [lbs].

Table 3

Surface	Frictional factor f
Steel on steel	0.15 ÷ 0.20
Rubber tire on polluted surface	0.5 ÷ 0.7
Rubber tire on asphalt	0.8 ÷ 1.0
Rubber tire on concrete	0.8 ÷ 1.0
Rubber tire on grass	0.4

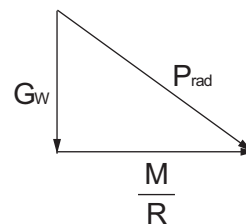
9. Radial motor loading: P_{rad} , daN [lbs]

When motor is used for vehicle motion with wheels mounted directly on motor shaft, the total radial loading of motor shaft P_{rad} is a sum of motion force and weight force acting on one wheel.

G_w - weight held by wheel;

P_{rad} - total radial loading of motor shaft;

M/R - motion force.



$$P_{rad} = \sqrt{G_w^2 + \left(\frac{M}{R}\right)^2}$$

In accordance with calculated loadings the suitable motor from the catalogue is selected.

