## Proportional Amplifier EBM-300308-DS-MOBI



- can control 3 directional valves ( 6 proportional solenoids)
- can be used with various demand signals
- can be used immediately; no programming needed
- output stages are protected against switch-off peaks


## 1 Description

### 1.1 General

The proportional amplifier EBM-300308-DS-MOBI can control three proportional directional valves. The card has input terminals for a voltage demand signal for each axis. An inductive joystick, type FGE, can be used as a demand-signal source, alternatively one potentiometer per axis can be used. Three different types of joystick can be selected by applying different reference voltages at an input. An integral ramp generator (demand-signal integrator) can be activated. When a step signal is applied to the input of the ramp generator, the output voltage changes linearly with time. This causes the respective output current to change in a similar linear manner until it reaches the value that corresponds to the new demand signal level. By using the ramp feature, a rapid change in the demand signal is translated into a gradual change in the output current. The ramp time is adjustable between 0 and 5 seconds for all three axes jointly. The current at the power outputs varies linearly with the voltage at the demand signal input (see diagram, sect. 8.1). For safety reasons, there is no output current until the demand signal rises to a minimum threshold value. With two trimming potentiometers for each axis, the minimum current $\left(I_{\text {min }}\right)$ and maximum current $\left(I_{\max }\right)$ can be set for each axis independently. The output stages feature internal protection against switch-off spikes. The amplifier is provided with a 'Busy' output - the supply voltage to the electronics system is present at this output when current is flowing to any of the solenoids. The proportional amplifier can be enabled or disabled via an "Enable" input. If a variance between the output current and the required value exists for more than 1000 milliseconds, the output is disabled and will be re-enabled only after the respective axis has come to a standstill. This allows a cable break or short circuit to be detected. If only two proportional directional valves are to be used, but complemented by a seat-type directional valve, this option can be selected via an input. In this case, the input for the third axis controls this directional seat valve. To avoid operational prob-
lems, the nominal voltage of the solenoid coils should be matched to the power supply voltage.

### 1.2 Application example

The EBM-300308-DS-MOBI proportional amplifier is used for controlling three proportional directional valves (three axes / six solenoids) or two proportional directional valves and one seat-type directional valve. The three axes can be controlled independently of each other. The current compensation feature ensures that the output current is unaffected by fluctuations in the coil temperature or supply voltage.
Application possibilities:

- Agricultural machinery
- Municipal vehicles
- Forestry machines
- Construction machinery


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## 2 Technical data

| General Characteristics | Unit | Description, value |
| :---: | :---: | :---: |
| Power supply | V DC | $12 . .30$ smoothed DC. Ripple < 10\% |
| Special features |  | Power supply input is protected against reverse polarity |
| Reference voltage | V DC | $\begin{aligned} 5 \mathrm{~V} & \max .150 \mathrm{~mA} \\ 10 \mathrm{~V} & \max .150 \mathrm{~mA} \end{aligned}$ |
| Demand signal voltage from demand-signal source Ain0 - Ain2 | V DC | $2,5 \mathrm{~V}$ $+/-2,3 \mathrm{~V}$ FGE type 1 <br> $4,5 \mathrm{~V}$ $+/-1,0 \mathrm{~V}$ FGE type 2 <br> $4,5 \mathrm{~V}$ $+-4,0 \mathrm{~V}$ FGE type 3 |
| Adjustable min. current per axis ( $I_{\text {min }}$ ) | A | 0,2 ... 1,2 |
| Adjustable max. current per axis ( $I_{\text {max }}$ ) | A | 0,8 ... 2,5 |
| Max. permissible current per axis | A | 2,5 |
| Dither frequency | Hz | 200 |
| Busy output Out6 |  | Low: 0 V <br> High: $\mathrm{U}_{\mathrm{KL} 30}$ (Busy) / $\mathrm{I}_{\max } 2,5 \mathrm{~A}$ |
| Enable input Ain5 |  | Low: 0 V (Enable) <br> High: $U_{\text {KL30 }}$ (Disable) |
| Joystick selection Ain3 |  | $\begin{array}{ll} 0,0 \mathrm{~V}<=U_{\text {Ain3 }}<0,5 \mathrm{~V} & \text {-> type } 1 \\ 0,5 \mathrm{~V}<=U_{\text {Ain3 }}<5,5 \mathrm{~V} & \text {-> type } 2 \\ 5,5 \mathrm{~V}<=U_{\text {Ain3 }}<=U_{\text {KL30 }} & \text {-> type } 3 \end{array}$ |
| Ramp time for 100\% Ain4 |  | $\begin{array}{ll} U>=0,0 \mathrm{~V} & ->\text { no ramp function } \\ U>=5,0 \mathrm{~V} & ->1 \mathrm{sec} \\ \mathrm{U}>=10,0 \mathrm{~V} & ->5 \mathrm{sec} \end{array}$ |
| Control of third axis, proportional or on/off Ain6 |  | $\mathrm{U}=0,0 \mathrm{~V}$ or not connected $->$ third axis controls a prop. directional valve $\mathrm{U}=10,0 \mathrm{~V}$-> third axis controls a directional seat valve |
| Plug connection |  | Tyco junior power timer 22-pin |
| Protection class |  | IP53 |
| Operating temperature | ${ }^{\circ} \mathrm{C}$ | -40 ... +80 |
| Dimensions |  | $(95 \times 65 \times 35) \mathrm{mm}$ |
| Cable lengths and cross sections |  | For $1 \mathrm{~mm}^{2}$ the max. cable length is 100 meters |

## 3 Dimensions



## 4 Block diagram



## 5 Functions

### 5.1 Joystick selection

| The user can select from three different types of joysticks: |  |  |
| :--- | :--- | :--- |
| Voltage at Ain3 | Demand signal voltage from <br> demand-signal source | Example for joysticks |
| $0,0 \mathrm{~V}<=\mathrm{U}_{\text {Ain3 }}<0,5 \mathrm{~V}$ | type $12,5 \mathrm{~V}+/-2,3 \mathrm{~V}$ | FGE*-MT1V*** $\mathrm{G}^{* *} \mathrm{JS3}$ |
| $0,5 \mathrm{~V}<=\mathrm{U}_{\text {Ain3 }}<5,5 \mathrm{~V}$ | type $24,5 \mathrm{~V}+/-1,0 \mathrm{~V}$ | FGE2-**-G12/JS4 |
| $5,5 \mathrm{~V}<=\mathrm{U}_{\text {Ain3 }}<=\mathrm{U}_{\text {KL30 }}$ | type $34,5 \mathrm{~V}+/-4,0 \mathrm{~V}$ | FGE1-**G**JC1 |

### 5.2 Ramp function

A ramp function can be activated by wiring the input Ain4. A step change in the demand signal causes a linear change of the solenoid current.

| Voltage at Ain4 | Ramp time for $100 \%$ |
| :--- | :--- |
| $U_{\text {Ain4 }}=0,0 \mathrm{~V}$ | no ramp function |
| $\mathrm{U}_{\text {Ain4 }}=5,0 \mathrm{~V}$ | 1 sec |
| $\mathrm{U}_{\text {Ain4 }}=10,0 \mathrm{~V}$ | 5 sec |


| When voltages between the specified values are applied, the ramp time is calculated accordingly: |  |
| :--- | :--- |
| Voltage at Ain4 | Ramp time for $100 \%$ |
| $0,0 \mathrm{~V}<=U_{\text {Ain4 }}<5,0 \mathrm{~V}$ | $\sim 0 \mathrm{sec}-1 \mathrm{sec}$ |
| $5,0 \mathrm{~V}<=\mathrm{U}_{\text {Ain4 }}<10,0 \mathrm{~V}$ | $\sim 1 \mathrm{sec}-5 \mathrm{sec}$ |

### 5.3 Selecting the type of output circuit for the third axis

| There is a choice between proportional directional valve and seat-type on/off directional valve |  |
| :--- | :--- |
| Voltage at Ain6 | Function |
| $U=0,0 \mathrm{~V}$ or not connected | proportional |
| $U=10,0 \mathrm{~V}$ | directional seat valve |

### 5.4 Additional functions

- To activate the module, connect the terminal KL 15 (module enable) to the power supply (KL 30).
- The busy output rises to the supply-voltage level as soon as any proportional output is energised.
- If the enable input is at the supply-voltage level, the proportional outputs are disabled.


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## 6 Connection diagram

### 6.1 Connecting a type 1 joystick, e.g. FGE*-MT1V*** $G^{* *} J S 3$



If only two axes are used with this joystick model, connect the free analogue input in parallel with the analogue input of another axis.

### 6.2 Connecting a type 2 joystick, e.g. FGE2-**-G12/JS4



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### 6.3 Connecting a type 3 joystick, e.g. FGE1-**G**JC1



When connecting a type 3 joystick, connect the analogue inputs for the unused axes to the 5 V reference voltage.

### 6.4 Connection example: FGE2-**-G12/JS4 joystick with two seat-type directional valves

In the following connection example, the two outputs OUT4 and OUT5 are used for operating seat valves. For this purpose, the input Ain6 is connected to the 10 V reference voltage. In this example, the input Ain2 has been connected
with the input Ain0 ( X axis). If the joystick is now moved in the positive direction of the $X$ axis, the seat valve 1 (OUT4) will also be operated. If it is moved in the negative direction, however, seat valve 2 (OUT5) will be operated.


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## 7 Pin assignment

| Pin | Signal |  |
| :---: | :--- | :--- |
| 1 | CAN-H | not used |
| 2 | REF 10 | reference voltage 10 V |
| 3 | CAN-L | not used |
| 4 | REF 5 | reference voltage 5 V |
| 5 | OUT 0 | output proportional valve 1, X-axis |
| 6 | KL30/1 | power supply |
| 7 | OUT 1 | output proportional valve 2, X-axis |
| 8 | AIN 0 | analogue input X-axis |
| 9 | OUT 2 | output proportional valve 1, Y-axis |
| 10 | AIN 1 | analogue input Y-axis |
| 11 | GND | ground |
| 12 | AIN 2 | analogue input Z-axis |
| 13 | OUT 3 | output proportional valve 2, Y-axis |
| 14 | OUT 4 | analogue input joystick selection |
| 15 | AIN 4 | antput proportional valve 1, Z-axis |
| 16 | OUT 5 | output proportional valve 2, Z-axis |
| 17 | AIN 5 | enable signal |
| 18 | KL 15 | ignition (module-enable, connect with KL30/1) |
| 19 | OUT 6 | busy output |
| 20 | AIN 6 | selection of the third axis: proportional or seat-type directional valve |
| 21 | AIN 7 | not used |
| 22 |  |  |



## 8 Initial start-up

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Connect the proportional amplifier in accordance with the connection diagram.

Connect the proportional amplifier in accordance with the connection diagram. To select the joystick type, set the input Ain3 to the appropriate level. To adjust the ramp time, set the input Ain4 to the appropriate level or connect it to a potentiometer. After the power supply is switched on, the minimum and maximum currents for each axis can be set by means of the 6 potentiometers.

1. Turn the potentiometers for the minimum currents $I_{\text {min }}$ to their left end-stop and the potentiometers for the maximum currents $I_{\text {max }}$ to their right end-stop.
2. Move the joystick just far enough in one axis direction to energise the solenoid. Then turn the $I_{\text {min }}$ potentiometer up until the required minimum current is reached (adjustment range: $200 \mathrm{~mA}-1200 \mathrm{~mA}$ ).
3. Now deflect the joystick fully and set the required maximum current $I_{\text {max }}$ with the respective potentiometer (adjustment range: $800 \mathrm{~mA}-2500 \mathrm{~mA}$ ).
4. Repeat steps $1-3$ for all axes.

If the potentiometer value for $I_{\min }$ is greater than the value for $I_{\max }$, then the $I_{\max }$ value will automatically be used for $I_{\text {min }}$.

|  |  |
| :--- | :--- |
| Poti 5 | $I_{\text {max axis } Z}$ |
| Poti 4 | $I_{\text {min axis } Z}$ |
| Poti 3 | $I_{\text {max axis } Y}$ |
| Poti 2 | $I_{\text {min axis } Y}$ |
| Poti 1 | $I_{\text {max axis } X}$ |
| Poti 0 | $I_{\text {min axis } X}$ |



### 8.1 Set-value characteristic



| 1 | Switch-off due to broken cable / short circuit |
| :---: | :--- |
| 2 | Hydraulic working range |

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### 8.2 Energisation of the outputs

| Proportional directional valve | Joystick deflection | X axis | Y axis | Z axis |
| :---: | :---: | :---: | :---: | :---: |
| When the joystick is moved, the outputs Out0 - Out5 are energised as follows: | $\mathrm{U}>\mathrm{U}_{\text {middle }}$ | Out1 | Out3 | Out5 |
|  | $\mathrm{U}<\mathrm{U}_{\text {middle }}$ | Out0 | Out2 | Out4 |
| Directional seat valve | Voltage at Ain2 |  |  | Z axis |
|  | $\begin{aligned} & \mathrm{U}_{\text {Ain2 }}>2,8 \mathrm{~V}(\text { (FGE Typ 1) } \\ & \mathrm{U}_{\text {Ain2 }}>4,6 \mathrm{~V}(\text { FGE Typ 2) } \\ & \mathrm{U}_{\text {Ain2 }}>5,0 \mathrm{~V}(\text { FGE Typ 3 }) \end{aligned}$ |  |  | Out5 |
|  | $\begin{aligned} & \mathrm{U}_{\text {Ain2 }}<2,2 \mathrm{~V}(\text { (FGE Typ 1) } \\ & \mathrm{U}_{\text {Ain2 } 2}<4,4 \mathrm{~V} \text { (FGE Typ 2) } \\ & \mathrm{U}_{\text {Ain2 }}<4,0 \mathrm{~V} \text { (FGE Typ 3) } \end{aligned}$ |  |  | Out4 |

## 9 Ordering code

| Model | Code | Part number |
| :--- | :---: | :---: |
| Proportional amplifier | EBM-300308-DS-MOBI | 100034752 |

### 9.1 Accessories

Various types of joysticks or potentiometers are available for generating the demand signals. To connect the solenoids, type GDM 309 solenoid plugs or AMP can be used, de-
pending on the model. In the event of proportional valve malfunctions that are caused by long power leads, use connector plugs type GDM 209D.

| Type | Connection diagram | Data sheet | Ordering code | Note |
| :---: | :---: | :---: | :---: | :---: |
| Joystick FGE1-****JC1 | 6.3 | 100-P-700051 | 100020513 | model for 1 axis |
| Joystick FGE*_**-G12/JS4 | 6.2 | 100-P-700051 | 100016362 | model without gate, for 2 axes |
| Joystick FGE2-**-G12/JS4 | 6.2 | 100-P-700051 | 100018348 | model with gate, for 2 axes |
| Joystick FGE*-*2T***/J2A7 | 6.1 | 100-P-700051 | 100031751 | model with 2 buttons in the cylindrical handle, for 1 axis |
| Joystick FGE*-33-G**/JS3 | 6.1 | 100-P-700051 | 100232813 | model with cylindrical handle, one rocker switch and an enable switch, for 1 axis |
| Joystick FGE*MA3HA1VG**/JS3 | 6.1 | 100-P-700051 | 100031668 | model with multi-function handle, 4 buttons, one rocker switch on front and one on back, for 2 axes |
| Joystick FGE*-MT1V*** ${ }^{* * / J S 3}$ | 6.1 | 100-P-700051 | 100029699 | model with multi-function handle, 4 buttons, one switch on front, for 2 axes |
| Solenoid plug GDM309 |  | 100-P-70010 | 100064970 |  |
| Solenoid plug GDM209D |  | 100-P-70010 | 100014130 |  |
| Plug, AMP 22-pin |  |  | 100235935 | 22-pin plug with crimp contacts for connecting the EBM-300308-DS-MOBI proportional amplifier |

## 10 Fault Finding

Unless otherwise specified, terminal Gnd (earth) is the reference point



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    When connecting a type 2 joystick, connect the analogue input for the unused axis to the centre tap.

